EC1600

AUTO-RANGING ELECTRICAL CONDUCTIVITY SENSOR

PRODUCT USER MANUAL

EARTH SCIENCES

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Quality Assurance Statement

ISO9001 accreditation

ESS Earth Sciences is currently an AS/NZS ISO9001:2008 certified organisation.

This certification is evidence that sound practices are used to get high quality instrumentation to your organization within a reasonable time interval. Standard practices are used for all areas of manufacture, beginning with the efficient procurement of incoming orders, right through to shipment.

Stringent quality assurance procedures are applied to all aspects of manufacturing, including the calibration of scientific instruments against NATA traceable references. Every sensor is accompanied by a test and calibration certificate that can be used as reference information as well as evidence of sensor accuracy.

Terms of Warranty

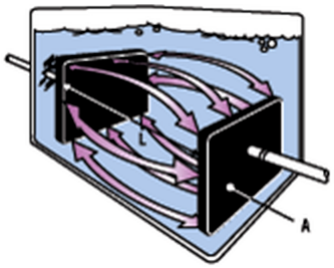
The warranty covers part or complete replacement, repair or substitution of new instrumentation that has failed in part or completely within the warranty period. While every effort has been made to supply robust and user friendly instrumentation, the warranty does not cover instruments incorrectly installed, misused or operated in conditions outside those specified. The warranty does not cover shipment costs for instrumentation, installation or removal and, under no circumstances whatsoever, indirect or consequential losses caused by the failed instrumentation.

ESS Earth Sciences believes the warranty conditions to be fair and just and in accordance with standard business practices worldwide. ESS Earth Sciences reserves the right to arbitrate any warranty issues and will ensure that warranty issues are treated with the highest standards of professional conduct.

At ESS Earth Sciences we believe your investment in our products and services is a good decision and we will therefore ensure all your requirements are met at all times, both now and in the future.

Conductivity - An Introduction

What is electrical conductivity?



Electrical conductivity* is a measure of how easily electrons flow through a material. For all materials, conductivity is proportional to the cross sectional area of the current path, and inversely proportional to the distance the current has to flow.

Conductivity can be measured from first principles by using a conductivity cell. This is a box containing a liquid, with two plates, each of area A separated by a distance L.

The first step to determining conductivity is to measure the conductance of the material, which is simply the ratio of the current to the voltage across the cell. The basic unit of conductance is the Siemen (S). We then compensate for the size of the cell to derive the specific conductivity C in S/cm. This is simply the product of measured conductance (G) and the electrode cell constant $C = G \times (L/A)$

How is conductance measured in practice?

For field use, it is not practical to use two plates separated in a cell. A common method of field conductivity measurement uses a miniaturized version of the conductivity cell. Two electrodes are separated by a short distance (typically 1 cm) and a voltage is connected across them, and the current is measured (In practice, a sinusoidal voltage is used to reduce DC effects, and four electrodes rather than two are used.) The dimensions are compensated for, and the conductivity is derived a similar manner to the conductivity cell.

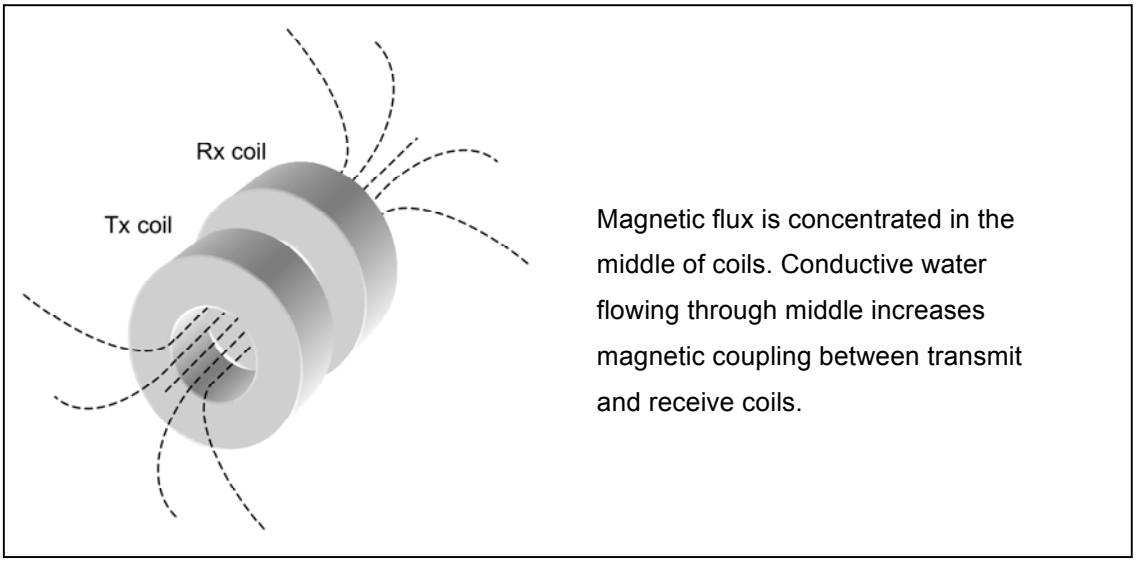
The above method is very common, it is simple to implement, and its operation is intuitively obvious. However it has a serious drawback: To work correctly, the electrodes must be in direct contact with the liquid. This leads to corrosion of the electrodes, resulting in unstable results, long term drift, and overall low reliability in the field.

How does the 1600 conductivity sensor work?

The 1600 EC sensor employs a different measuring technique. Instead of electrical contact probes, it uses an inductive (or magnetic) method to determine conductivity. By using this approach, there is no direct contact with the liquid. Although more difficult to implement, this toroidal method is inherently more reliable, and has very low drift compared with electrode type sensors, and will operate for many years, even in difficult environments.

Two coils are placed a known distance apart. One coil has an oscillating current applied that forms a magnetic field inside the coil centre. The other coil receives the magnetic flux produced inside the transmit coil. Because of the coil arrangement, the receiving coil will only receive signal when a conductive material is placed between the coils. If water is allowed to flow through the coil centre, impurities in the form of dissolved salts will provide the necessary magnetic coupling.

Note: Conductivity should not be confused with conductance, which is the inverse of the material's resistance.


Rx coil
Tx coil
Magnetic flux is concentrated in the middle of coils. Conductive water flowing through middle increases magnetic coupling between transmit and receive coils.

The above diagram shows how the sensor works. Transmit (TX) coil forms a magnetic flux inside the coil pair. Conductive water increases the magnetic coupling which is seen as a transfer of oscillating current in receiver (Rx) coil. The degree of transfer is an indication of water conductivity.

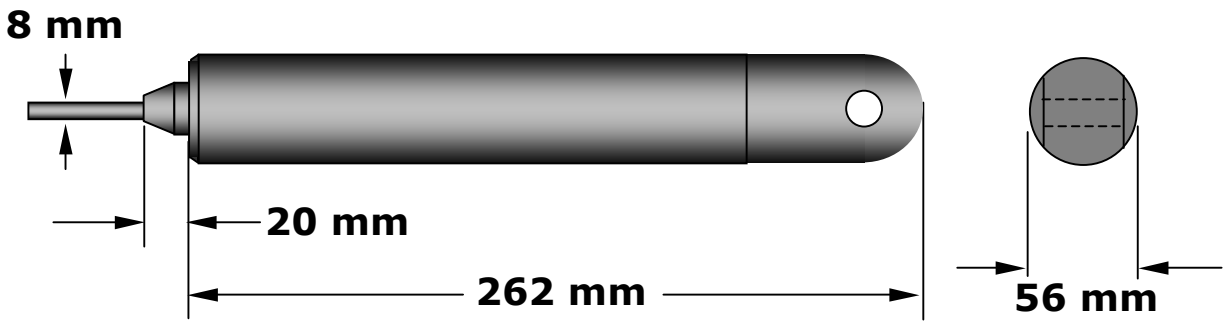
What is temperature compensation?

Like resistance, conductivity changes with temperature. The lower the temperature, the less the conductivity and this is because electrons find it harder to flow through dissociated salt molecules at lower temperature. This makes measurement confusing when actually trying to determine the water conductivity over a temperature range. To overcome this effect, conductivity measurements at any temperature are output as if the temperature is 25°C and is called *temperature compensated output.*

The relationship between compensated and non compensated (raw) output is linear and simply put, a percentage is added or subtracted from the raw measurement to determine compensated output. For the 1600 EC sensor, the compensation is set at approximately 2% per °C. For temperatures below 25 °C the proportion is subtracted and is added for temperatures above 25°C. Of course the temperature needs to be measured for compensation and therefore the 1600 EC sensor has an internal temperature sensor. As an additional feature, the 1600 EC sensor also has a separate temperature output available to loggers and controllers as a 4-20mA signal. Temperature compensation operates between 0 and 50°C, the typical expected water temperature for most environmental conditions.

$$Corrected\ EC\ at\ 25C\ in\ \frac{uS}{cm} = (Raw\ EC\ in\ \frac{uS}{cm})/(1 + 0.02(sample\ temperature - 25C))$$

Sensor description



The 1600 sensor is a fully submersible device used for measuring water conductivity. It is constructed from durable machined plastic components and epoxy resins. For reliability, there are no wetted metal components to corrode making this sensor suitable for high conductivity (high dissolved solids) application and even for water with high acidity. The 1600 EC sensor is designed for very long term deployment at unattended monitoring stations.

The sensor head is fully epoxy encapsulated and has a hole through the middle to allow the flow of water through it. It is here that the water provides magnetic coupling for the measurement to take place.

An 8mm diameter submersible rated cable is hardwired to the back of the sensor (length specified during ordering). Although care must be taken to secure the sensor at all times, the sensor may be suspended from the cable for short periods such as during installation.

Once installed and powered, the sensor will measure conductivity from 0 to 100,000 µS/cm.

The "dry" end of the cable has fife wires for supply, ground, SDI-12 and current output signals. Connectors can be fitted for direct connection to ESS Earth Sciences equipment (such as the 3500 logger) or custom connectors can be fitted upon request.

There are no moving parts on the 1600 EC sensor, and no serviceable components. This sensor is a dual output 3 wire current loop device plus SDI-12 as detailed in the *Installation* section.

Installation

Site Selection

Before installing a 1600 EC sensor it is recommended a suitable site be selected first. The installation and maintenance complexity as well as the reliability of the instrument in critical applications depends on the site chosen and the length of cable required can then be determined.

Well-chosen sites:

- slow flowing water (no stratification)
- minimal or no accumulation of debris around sensor
- easy and safe access, away from waterway traffic
- sensor head is always submerged in at least 200mm of water
- sensor head is at least 100mm from bottom and at least 50mm from any metal
- sensor cannot be dislodged during high flows

Avoid sites with:

- very low or stagnant water flows
- where debris can accumulate inside sensor head
- excessive air bubbles in water
- difficult or unsafe access
- high siltation rates
- where sensor will be exposed in air during low flows

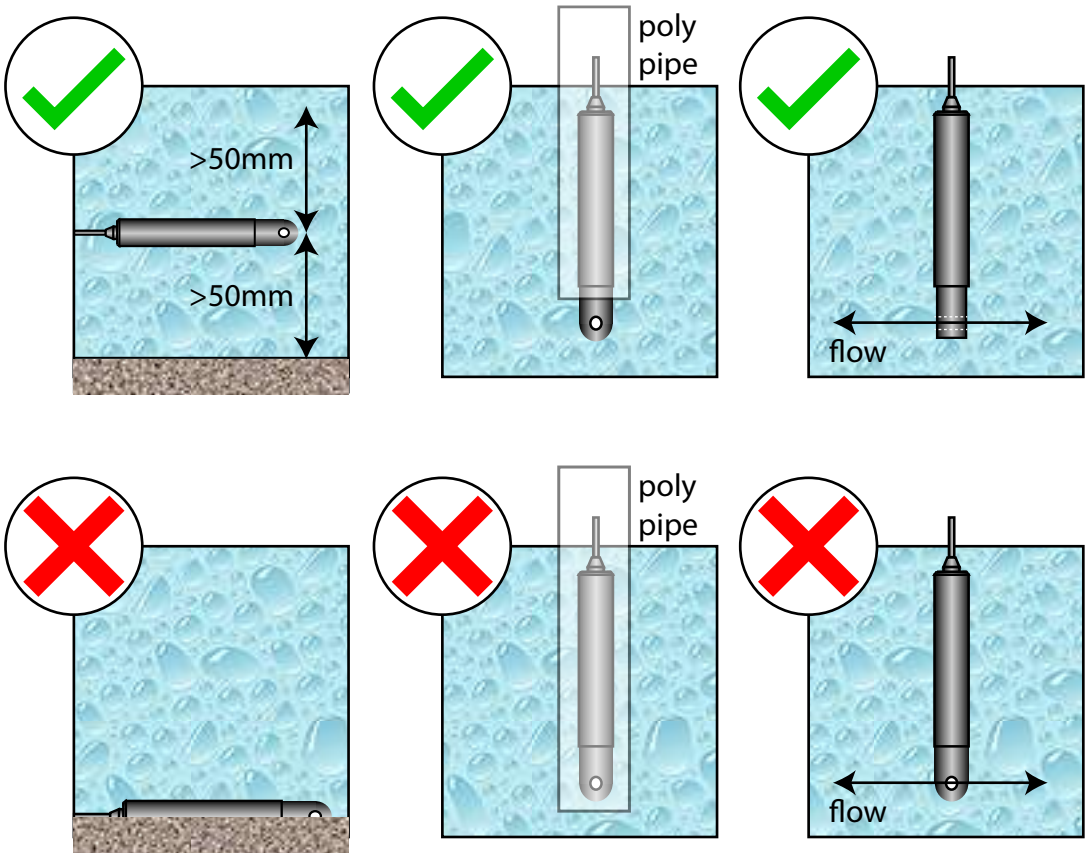
The following is also recommended for EC sensor installation

- Install the sensor out of direct sunlight, especially when in shallow water. Sunlight will heat the sensor head to produce a false temperature and compensated EC reading.
- Algae will tend to grow within the sensor hole. This can be minimized by covering the sensor with a shield to make the head as dark as possible. No sunlight means no algae
- Silt can accumulate in the sensor hole. Install the sensor so water can flow through the hole.

Typically, most sites that are already equipped with hydrographic instrumentation can be used for installation of the 1600 EC sensor.

Installation Orientation

For correct installation, the following recommendations apply:



With the exception of the sensor head (the part with the hole through it), the rest of the sensor can be completely covered by an installation tube. If 50mm ID poly tube is used for installation, a suitable compression gland is available from irrigation hardware suppliers. The sensor outside diameter is smaller than the compression gland internal diameter and can be clamped easily and securely using this method. When this system is used, the sensor head must protrude from the gland by at least 60mm.

Sensor Clearance

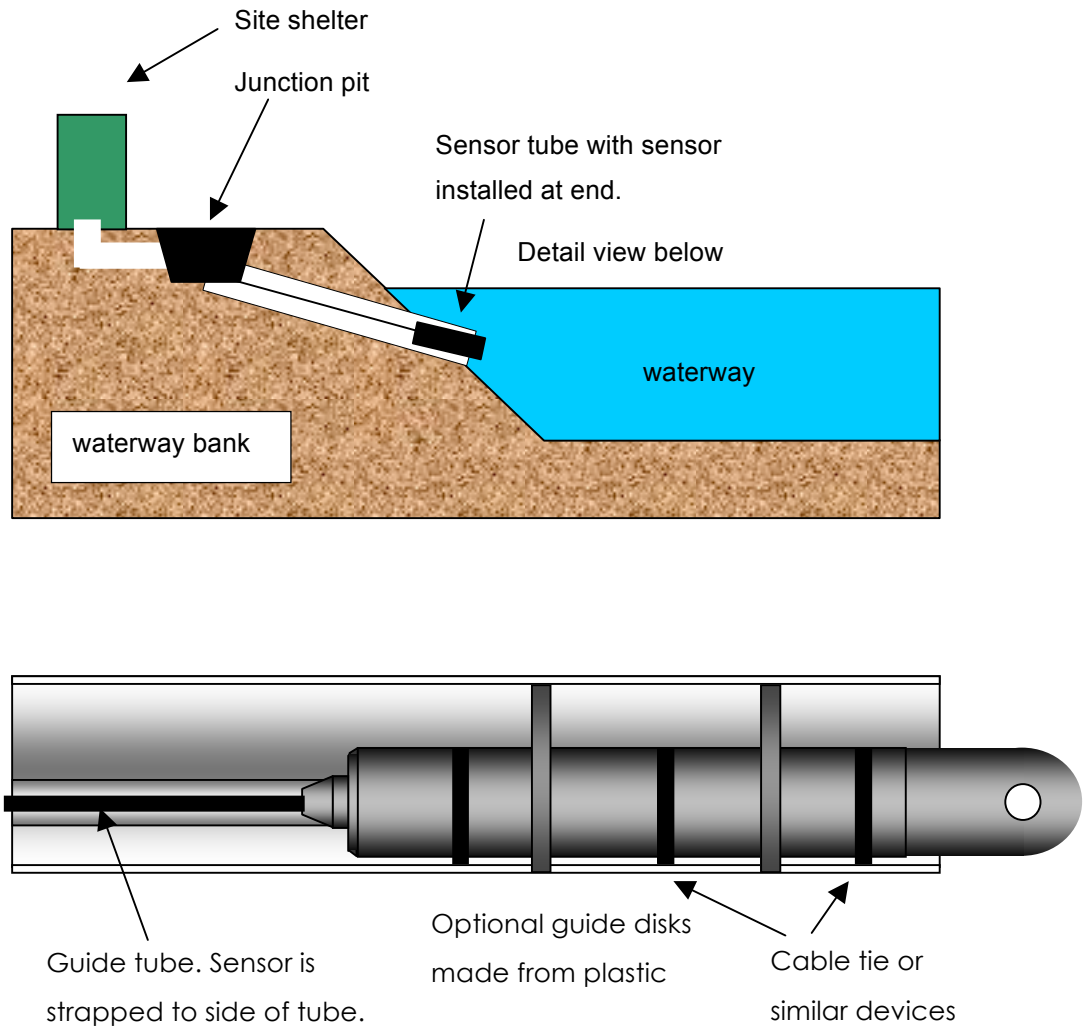
Correct orientation of the sensor will help to reduce the buildup of silt and debris within the hole in the center of the EC head. Where algal blooms are likely it is recommended the sensor is covered with a sun shield, keeping the sensor in the shade, thereby reducing algae buildup. When installing a shield, ensure the shield clears the sensor head by at least 50mm. The shield should ideally be installed 100mm from the sensor, and cover the sensor sufficiently from direct sunlight. A shield will also prevent excessive temperature variations.

Site preparation

Before the sensor can be installed, the site must be prepared to ensure the sensor will be secured, protected and serviceable.

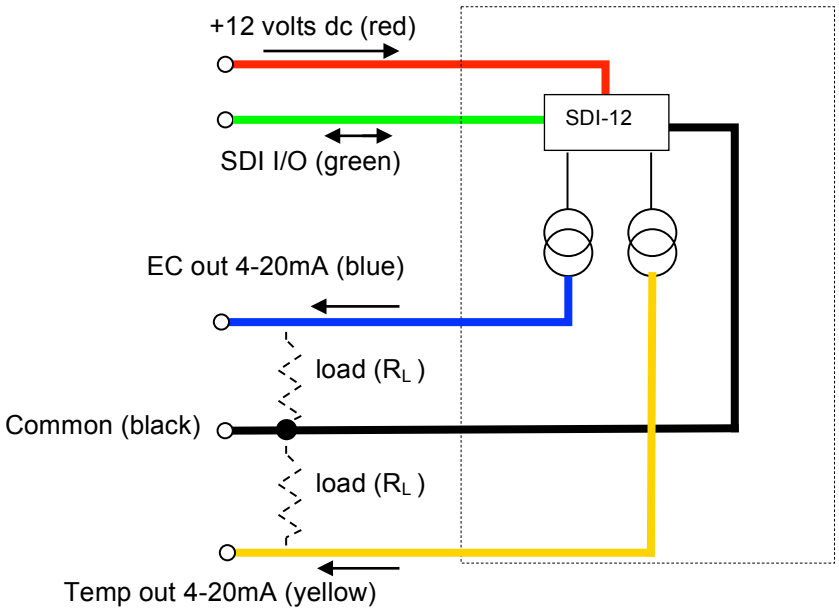
The following recommendation is based on typical installation methods practiced by today's hydrographers. Several variations of this method are used to suit particular applications.

Please study the diagram below. Site preparation involves the installation of a larger plastic tube along the waterway bank as shown. The tube should ideally be continuous but may also be made from sections. One end of the tube must be installed into the water ensuring the sensor optical path will not be obstructed according to the previous section *Sensor Clearance*. The other end can be terminated in a junction pit that is large enough so that the sensor can be inserted from the pit. Typically, an underground electrical pit is used as this also allows a sensor carrier assembly to be inserted easily. The pit must be installed on a stable part of the bank that cannot erode.

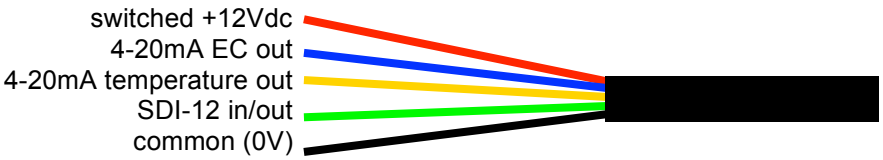


EC1600 Electrical Connection

SDI-12 and 4-20mA connections



The EC1600 is an SDI-12 sensor plus two 3 wire current loop devices



Conductor Colour	**Conductor Designation**	**Requirement**	**Connector 5-pin**
red	switched +12vdc input	80mA min	A
blue	4-20mA output, EC	Source, max 120 Ohm load	B
black	Common	0V dc	C
yellow	4-20mA output, Temp	Source, max 120 Ohm load	D
green	SDI-12 in/out		E

4-20mA Interface

To obtain a measurement from the 1600 sensor:

- Install the sensor according to recommendations in Section *Installation*.
- Apply power to the sensor
- 2 x 4-20mA current output will be produced at the respective outputs.
- Conductivity and temperature data is available on the SDI-12 bus

A current output signal will be available for measurement after 1 second. For power conserving applications, the sensor can be switched off immediately after the reading is attained. The sensor can also be left on continuously if required.

The 4-20mA current output will be available for reading 1 second after switched power is applied.

With proper care and routine maintenance, the sensor can be left operating unattended for several months. Of course, as each application will be different, it is recommended that the total time between services is determined experimentally.

SDI-12 Interface

The SDI-12 interface of the EC1600 handles all of the communication and power down features of the SDI-12 protocol.

All standard SDI-12 commands are supported. In addition, extended commands can be used to calibrate sensor outputs. Each of the measurements can be scaled and offset with user supplied calibration coefficients. The factory sets these parameters so the output is in µS/cm.

Any changes to these parameters should take into account their factory calibration values as these have been established by measurement for each sensor. The SDI-12 Interface also has an on board temperature sensor.

The interface has been fully tested with the NR Systems SDI-12 Verifier.

Operation

Standard SDI-12 Commands

The commands assume that the sensor address is 0, but any address could be substituted into the commands below. "\r\n" is carriage return and line feed characters.

Command	Description
?!	Returns address of a single sensor on the SDI-12 bus
0!	Acknowledgment, returns same address
0An!	Change SDI-12 address to n (i.e. n=5)
0I!	Query sensor information
0M!	Begin a measurement. Then use 0D0! To display result.
0D0!	Get data – use this after a 0M! Command. 5 values are being returned: EC25, EC, Temperature, Raw_EC, Raw_Temperature.
0MCD0!	Measure and display as above, include a CRC (as defined in the SDI-12 standard)

Symbols and Units:

EC 25: Compensated conductivity at 25°C in µS/cm.

EC: Conductivity in µS/cm

Temperature: Temperature in ºC

Raw_EC EC in ADC counts

Raw_Temperature: Temperature in ADC counts

The display command **0D0!** produces 5 values in this sequence:

id+EC25+EC+Temperature+Raw_EC+Raw_Temperature

Note: The value for EC25 is always 0 at present.

Example `command` and **`response`**:

```
0M!
00015

0D0!
0+00000+00774+20.51+000977+00538

0I!
013ES&S  EC16000.8 160159
```

EC1600-specific SDI-12 Commands

The following list shows EC1600 specific commands that have been implemented in addition to the required commands of the SDI-12 standard.

Depending on the utility used, the commands need to be completed by a preceding address character (in the examples below we use **0** - zero) and terminated by an exclamation mark.

For example, the command Xuptime needs to be send to the device with the address 0:

0Xuptime!

Command Description	**SDI-12 Command**	**Example / comment**
General Maintenance and Setup Commands		
Read serial number	0Xsn!	160161
Reset device	0Xreset 1!	
Check uptime	0Xuptime!	Seconds of runtime
Status information	0Xstatus!	
Firmware version	0Xversion!	
Set SDI-12 address	0Xaddr 5	In this example it sets SDI-12 address from 0 to 5. This is an alternative to the standard SDI-12 nA! command
Fix measurement range to lower range	0Xrfix 0!	Fix range to 0 to 25000 uS/cm
Fix measurement range to upper range	0Xrfix 1!	Fix range to 25000 to 100000 uS/cm
Fix measurement range to auto-ranging	0Xrfix 255!	Set range to auto (default)
Query 4-20mA Interface – what **temperature** is **4mA**?	0Xcte 4!	0.0
Set temperature at 4mA	0Xcte 4 [<float>]!	Can be any floating point value from 0.0 to 50.0
Query 4-20mA Interface – what **temperature** is **20mA**?	0Xcte 20!	50.0
Set temperature at 20mA	0Xcte 20 [<float>]!	Can be any floating point value from 0.0 to 50.0
Query 4-20mA Interface – what **EC value** is at **4mA**?	0Xcec 4!	0.0
Set temperature at 4mA	0Xcec 4 [<float>]!	Can be any value from 0.0 to 100000.0
Query 4-20mA Interface – what **EC value** is at **20mA**?	0Xcec 20!	100000.0
Set temperature at 20mA	0Xcec 20 [<float>]!	Can be any value from 0.0 to 100000.0
Measurement commands		
Take a measurement	0Xm!	Takes a measurement and displays the result (faster than the 2-step standard SDI-12 command).

The measurement command 0Xm! produces 5 values in this sequence:

temp_adc temperature ec_adc ec ec25 status Vcc range

Example result: 0432 5.76 02359 2281.4 0.0 OK!! 11.46 r0

Example program to read SDI-12

The following program can be used with the Campbell Scientific CR1000 logger.

```
Program name: CR1000 sample display reading.CR1
'Date written: 3/06/2009 using the CRBasic programming tool from
'Campbell Scientific LoggerNet 3.4.1

'This program is used to test the SDI-12 Interface using a
'Campbell's CR1000 logger.
'
'Sensor powered from 12V terminal and a G terminal, and with SDI-12
'on C1 terminal.
'Logger   C1----green------Sensor SDI-12
'         12V---red--------Sensor Power +ve
'         G ----black------Sensor Ground

'The program below will collect data each second from the five SDI-12
'Interface channels.

'Use one of the Data Displays from the LoggerNet Connect Screen.
'Set the table cells to sdidata(1) to sdidata(5).
'The information from each of the four channels of the SDI-12 Sensor
'Engine will be displayed and updated every second.


Public sdidata(5)  'sdidata(1) ec25
                   'Sdidata(2) ec
                   'Sdidata(3) temperature
                   'Sdidata(4) adc_conductivity
                   'Sdidata(5) adc_temperature


BeginProg
  Scan(1,Sec, 3, 0)
    SDI12Recorder(sdidata, 1, "0", "M!", 1.000, 0)
  NextScan
EndProg
```

Maintenance

The 1600 sensor will require little periodic maintenance to ensure that measurements remain accurate. While all wetted components are no metallic and cannot corrode in high salt or acidity liquids. Debris, silt and algae lodged in the hole can cause inaccurate readings. It is recommended the sensor is checked during every visit, or at least every 3-6 months. You may find the sensor will not require any maintenance for even longer periods however, warmer climates or high silt laded rivers and streams can accelerate these effects.

General

- Ensure the sensor is not affected by debris, silt or algae (or marine growth). The sensor should be removed from its installed location for a thorough inspection. Using the recommended installation method outlined in the section Installation, removal should be easy and maintenance staff do not need to enter the waterway
- Ensure the installation is sound and the sensor is still secure from moving and there are no obvious signs of erosion or damage.

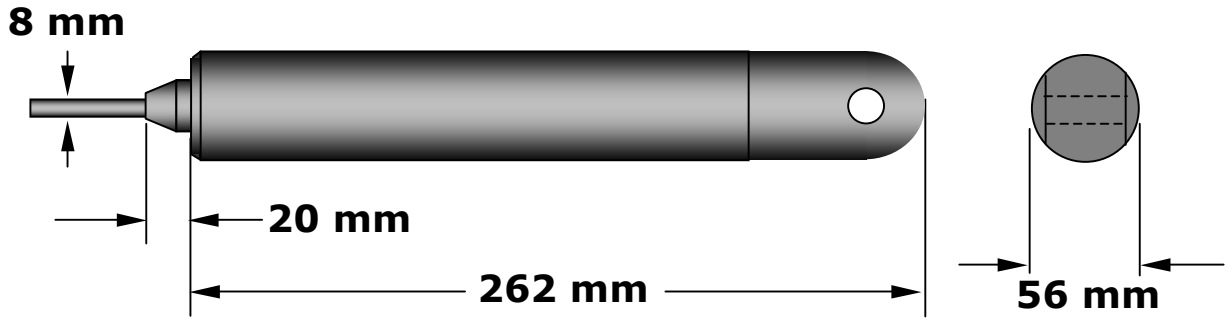
Calibration check

The sensor output can be checked against a reference instrument if it is available. Ideally, the measurement should be taken in the same solution as the sensor while the sensor is installed. If there is a large difference, an installation problem may be highlighted. All sensor measurements should be within the specified accuracy.

- Compare the sensor measurement to that of the reference instrument.
- Ensure the reference instrument calibration error is also known.

Specifications

Range	200 to 100,000µS/cm		
Accuracy	EC linearity	< 2% over the range 0 to 30°C	
	Temperature	< 0.2°C over the range 0 to 30°C.	
Temperature range	-10 to 60°C storage (in dry environment), operating: 0 to 50°C		
Response Time	2 seconds to full accuracy		
Type	Magnetic inductive coupling		
SDI-12 Output	EC in µS/cm (standard)		
4-20mA Output	Scaled to maximum range.		
	EC:		
	4mA:	0µS/cm	(user adjustable)
	20mA:	100,000µS/cm	(user adjustable)
	Temperature:		
	4mA:	0 °C	(user adjustable)
	20mA:	50 °C	(user adjustable)
Power Supply	12VDC, current capability >500mA		
	0.3mAh per reading on average (typical)		
Surge	Secondary surge protection, Can absorb 0.6J of energy		
Dimensions	262 long, 56 dia (mm)		



Product Return Form

As part of our Quality Assurance initiative, and to improve response time, we request that the forms below are completed in as much detail as possible for product returns.

OPERATOR INFORMATION				
Name and contact details				
Company				
Date/Time				
Logger Site				
Location of product				
PRODUCT INFORMATION				
Model				
Serial number				
S/W version number(s)				
H/W version number(s)				
SOFTWARE USED				
Download program				
Remote or Local download				
Other software used				
CONFIGURATION				
Logger				
Length of tube				
Last logged values				
Measurement interval				
SITE - Describe site. Is unit in protective hut or enclosure? List any other sensors which are used at the site. Estimate cable length to sensors				
POWER SUPPLY				
Battery				
Voltage / Capacity				
Internal/External				
Solar/Mains charger				
Measured battery volts				
Solar Panel				
Voltage/Capacity				
Regulator make / model				
Switching/Linear regulator				
Mains supply				
COMM PORT		SDI-12 port		4-20mA
EARTHING -Describe any special earthing arrangements in place.				

DESCRIPTION OF PROBLEM How did the problem manifest itself? Weather conditions while fault occurred (especially temperature) What commands were being used (SDI12 or serial)? *If possible, list the exact commands used, and the sequence. List the commands sent through the logger* What action was taken to get the unit going again? Have you noticed anything in common with the last time there was a fault? Was the unit permanently disabled, or is the fault intermittent? Is this the first time the fault occurred? Is there anything unusual about this site compared to other sites? Is there any other equipment or facilities (e.g. local power lines) which could cause interference? Please list any other issues relating to the site or the fault.	

DELIVERING WATER MONITORING SOLUTIONS

2600 Turbidity Sensor

The 2600 Turbidity sensor is a miniature backscatter nephelometer that detects turbidity and suspended solids in water. Applications include rivers / streams / irrigation runoff water quality, sediment transportation, aquaculture, waste water quality, EPA compliance monitoring.

LevelPro 6100

The LevelPro 6100 advanced liquid level sensor is used to measure water level determination 0-70 metres. Applications include river / irrigation water level, tidal monitoring, groundwater level & landfill monitoring, dam, tank, reservoir levels, waste water monitoring, food warning systems, process industry liquid level.

PumpPro 6150

The PumpPro 6150 combines an integrated air compressor module and levelpro 6100 advanced liquid level sensor to form a fully self contained hydrostatic pressure sensor designed to measure water and liquid levels reliably and accurately.

Dipmeter

The Water Level Indicators Dipmeters are typically used to measure the depth of water levels in boreholes, standpipes or observation wells.

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